



Course Specifications											
Program(s) on which this course is given:			Aerospace	Aerospace Engineering							
Department offering the program:			Departmen	Department of Aerospace Engineering							
Department offering the course:			Departmen	Department of Aerospace Engineering							
Academic Level:				MSc	MSc						
Date	e* 1		• \	2014-2015	2014-2015						
Semester (based o	n final exa	am tin	ning)	V∐Fall							
A- Basic Information											
1. Title:	Special Topics in Control		Aeronautical	Code:		AER657					
2. Units/Credit hours per week:	Lectures		2	Tutorial		Practica	al		Total	2	
B- Professional Information											
1. Course descript	se description: The scope of the course is quite broad. This is in order to show the multidisciplinary rol of nonlinear dynamics and control. In particular, adaptive control, and Lypunov stabilit theory is provided. The objective of the stability analysis is to determine the system behavior without solving the differential, or difference, equations modeling the system.						ry role ability system em.				
		a) Knowledge and Understanding									
		Different approaches of adaptive control.									
		Different approaches of nonlinear control.									
		Some advanced control techniques.									
		b) Intellectual Skills									
		Simulate advanced control systems.									
2. Intended I	earning	Analyze advanced control systems.									
Outcomes of Cou		Design advanced control systems.									
		c) Professional and Practical Skills									
		Use computer software packages to design, simulate, and evaluate advanced control systems.									
		d) General and Transferable Skills									
		Prepare effective and informative technical reports and present results on advanced									
		Communicate effectively with colleagues to interchange knowledge and information in advanced control systems.									
3. Contents											
Торіс			Total hours	Lectures ho	ours		Tutoria	al/ Practical h	ours		
Adaptive Control Systems.											

Торіс	Total hours	Lectures hours	Tutorial/ Practical hours
Adaptive Control Systems.			
Process Modelling and Identification for			
Use in Self-tuning Controllers			
Algebraic Methods for Self-tuning			
Controller Design			
Phase Plane Analysis			
Describing Function Analysis			

Fundamentals of Lyapunov	Theory						
		Lectures (<i>J</i>)	Practical Training/ Laboratory (J)	Seminar/Workshop ()			
4. Teaching and Learning Meth	ods	Class Activity (J)	Case Study ()	Projects (J)			
		E-learning (0)	Assignments /Homework (/)	Other:			
5. Student Assessment Methods							
Assessment Schedule			Week				
-Assessment 1; Project Assignme	nts		3,5,7,9				
-Assessment 2; Presentations			10				
-Assessment 3; Midterm Exam			9				
-Assessment 4; Final Exam			16				
Weighting of Assessments							
-Mid-Term Examination			10				
-Final-term Examination			80				
-Project			5				
-Class Test			5				
-Total			100				
6. List of References							
V. Bobal, J. Bohm, J. Fessl and J. Machacek, "Digital Self-tuning Controllers: Algorithms, Implementation and							
Applications", Springer-Verlag London Limited, 2005.							
Jean-Jacques E Slotine, Weiping Li, "Applied Nonlinear Control", Prentice Hall, 1991							
Roland S. Burns, "Advanced Control Engineering", Butterworth-Heinemann, 2001.							
Stanislaw H. Zak, "Systems and Control", Oxford University Press, 2003.							
Library resources, Internet search of periodicals							
7. Facilities Required for Teaching and Learning							
Computer lab							
Course Coordinator: Prof. Gamal El-Bayoumi							
Head of Department: Dr. Ay	man H.	Kassem					