



|   |                         |   | <b>Course Speci</b>           | fications                           |             |              |                       |       |  |  |
|---|-------------------------|---|-------------------------------|-------------------------------------|-------------|--------------|-----------------------|-------|--|--|
| Program(s) on wh                                      | ich this c              | ourse is given:   | : Aerospace Eng               | Aerospace Engineering               |             |              |                       |       |  |  |
| Department offering the program:                      |                         |   |                               | Department of Aerospace Engineering |             |              |                       |       |  |  |
| Department offering the course:                       |                         |   | Department of<br>MSc          | Department of Aerospace Engineering |             |              |                       |       |  |  |
| Academic Level:<br>Date                               |                         |   | Misc March 23 2015            |                                     |             |              |                       |       |  |  |
| Semester (based on final exam timing)                 |                         |   | □J Fall □ Spring              |                                     |             |              |                       |       |  |  |
| A- Basic Infor  | mation                  |   |                               |                                     |             |              |                       |       |  |  |
| 1. Title:   | Intelligent Control (2) |   | Code: AER 758                 |                                     |             |              |                       |       |  |  |
| 2. Units/Credit                                       | Lectures 2              |   | Tutorial                      | 1 F                                 | Practical   |              | Total                 | 3     |  |  |
| hours per week:                                       |                         |   |                               |                                     |             |              |                       |       |  |  |
| <b>B-</b> Professiona                                 | l Infor                 | mation  |                               |                                     |             |              |                       |       |  |  |
| 1. Course description:<br>ar<br>pa                    |                         | This course introduces the concepts of advanced intelligent control design of nonlinear autonomous vehicles using advanced artificial intelligent controllers based on Fuzzy logic and neural networks and heuristic optimization methods such as genetic algorithms and particle swarm optimization. |                               |                                     |             |              |                       |       |  |  |
|   |                         | a) Knowledge and Understanding  |                               |                                     |             |              |                       |       |  |  |
|   |                         | Student will understand the basics of artificial neural networks  |                               |                                     |             |              |                       |       |  |  |
|   |                         | Student will understand the basics of Fuzzy logic   |                               |                                     |             |              |                       |       |  |  |
|   |                         | Student will understand the basics of genetic algorithms and particle swarm optimization  |                               |                                     |             |              |                       |       |  |  |
| 2. Intended Learning<br>Outcomes of Course<br>(ILOs): |                         | b) Intellectual Skills  |                               |                                     |             |              |                       |       |  |  |
|   |                         | Student will be able to analyze control problem using Matlab neural networks toolbox  |                               |                                     |             |              |                       |       |  |  |
|   |                         | Student will be able to analyze control problem using Matlab fuzzy logic toolbox  |                               |                                     |             |              |                       |       |  |  |
|   |                         | Student will be able to formulate and solve optimization problems using genetic   |                               |                                     |             |              |                       |       |  |  |
|   |                         | algorithms and particle swarm d) General and Transferable Skills  |                               |                                     |             |              |                       |       |  |  |
|   |                         | Student will be able to design a controller using intelligent techniques  |                               |                                     |             |              |                       |       |  |  |
| 3. Contents   |                         | Student will  |                               | ontroller usi                       | ng mieniger | n techniques | •                     |       |  |  |
|   |                         |   | <b>T</b> ( ))                 | <b>T</b> ( <b>1</b>                 |             | <b>T</b> 4 • |                       |       |  |  |
| TopicNeuralNetworkArchitecturesfor                    |                         |   | Total hours                   | Lectures l                          | iours       | 1 utoria     | al/ Practica          | nours |  |  |
| Modeling and Control                                  |                         |   | 6                             |                                     | 4           |              | 2                     |       |  |  |
| Fuzzy Systems   |                         |   | 6                             |                                     | 4           |              | 2                     |       |  |  |
| Neuro-Fuzzy systems                                   |                         |   | 9                             |                                     | 6           |              | 3                     |       |  |  |
| Genetic Algorithms                                    |                         |   | 9                             |                                     | 6           |              | 3                     |       |  |  |
| Particle Swarm Optimization                           |                         |   | 6                             |                                     | 4           |              | 2                     |       |  |  |
| Applications of intelligent control                   |                         |   | 9                             |                                     | 6           |              | 3                     |       |  |  |
| 4. Teaching and Learning Methods                      |                         |   | Lectures ( <i>J</i> )         | Practical '<br>Laborator            |             | Semina       | Seminar/Workshop()    |       |  |  |
|   |                         |   | Class Activity $(\mathbf{J})$ | Case Study                          |             | Projects     | Projects ( <b>/</b> ) |       |  |  |
|   |                         |   | E-learning (0)                | Assignmen<br>/Homewor               |             | Other:       | Other:                |       |  |  |

| 5. Student Assessment Methods   |  |         |  |  |  |  |  |
|---|--|---------|--|--|--|--|--|
| • Assessment Sch  | edule  | Week    |  |  |  |  |  |
| -Assessment 1; Project A  | ssignments   | 3,5,7,9 |  |  |  |  |  |
| -Assessment 2; Presentati   | ions   | 10      |  |  |  |  |  |
| -Assessment 3; Midterm  | Exam   | 9       |  |  |  |  |  |
| -Assessment 4; Final Exa  | m  | 16      |  |  |  |  |  |
| Weighting of As   | sessments  |         |  |  |  |  |  |
| -Mid-Term Examination   |  | 20      |  |  |  |  |  |
| -Final-term Examination   |  | 40      |  |  |  |  |  |
| -Project  |  | 20      |  |  |  |  |  |
| -Class Test   |  | 15      |  |  |  |  |  |
| -Presentation   |  | 5       |  |  |  |  |  |
| -Total  |  | 100     |  |  |  |  |  |
| 6. List of References   |  |         |  |  |  |  |  |
| Intelligent Control Systen  | Intelligent Control Systems: An Introduction with Examples, Applied Optimization, ISSN 1384-6485 |         |  |  |  |  |  |
| AuthorsKatalin M. Hangos, R. Lakner, M. Gerzson, Springer Science & Business Media, 2001  |  |         |  |  |  |  |  |
| Intelligent Control: Biomimicry for Optimization, Adaptation, and Decision-Making in Computer Control and Automation, by K. M. Passino, Springer-Verlag, London, UK, 2004 |  |         |  |  |  |  |  |
| 7. Facilities Required for Teaching and Learning<br>Computer lab  |  |         |  |  |  |  |  |
| A<br>A  |  |         |  |  |  |  |  |
|   |  |         |  |  |  |  |  |
| Head of Department:     Dr. Ayman H. Kassem   |  |         |  |  |  |  |  |