

				Course Spec	cificatio	ns						
Program(s) on which this course is given:				PhD								
Department offering the program:				Aerospace Engineering								
Department offering the course:				Aerospace Engineering								
Academic Level:				Graduate- M. Sc.								
Date												
Semester (based on final exam timing)				🗆 Fall] Fall 🗌 Spring							
A- Basic Information												
1. Title:	Sensor Design			T	Code:		Aero 794					
2. Units/Credit	Lectures		2	Tutorial	1	Practic	ral		Total	3		
hours per week:			2	Tutonui	1	Tuett	Jui		1 otur	5		
B- Professional Information												
		The course covers fundamental sensor and instrumentation principles for Space systems. Systems discussed include satellite attitude determination sensors, measurement systems for magnetic field, force, temperature, pressure, aerodynamic and navigation sensors.										
		Topics covered in the course are:										
1. Course descripti	1- Forces and disturbances affecting space flight; Magnetic field, Van Allen belt, Solar wind, Aerodynamic forces, Gravity force. 2- Space vehicle attitude sensing and measurement 3- Design and Operation of Attitude Sensors: Sun Sensors , Earth and Horizon Sensors, Solar Sensors. 4- Measurement and actuation using magnetic field, magnetometers and magnetic torque rods. 5-Sensors measuring velocity and angular velocity- AVM devices. 6- Spacecraft Actuation and Control Devices, Reaction wheels, magnetorquers and thrusters. Selection and Sizing of Reaction wheels . 7- Other sensors, pressure, temperature, GPS.											
		a) Knowledge and Understanding										
		Knowledge and Understanding of the forces and disturbances affecting satellite and aircraft motion. Knowledge of the physical laws underlying these forces.										
		b) Intellectual Skills										
2. Intended L Outcomes of	earning Course	Ability to design the sensors based on the physical principles studied in the course.										
(ILOs):		 c) Professional and Practical Skills Principles and methodologies for Design, building and testing of instrumentation 										
		d) General and Transferable Skills										
Matlab (mathematical programming tool) - Simulations- SplidWorks software												
3. Contents							1					
Торіс					Tota	l hours	Lectu	ires hours	Tutorial/ Practical hours			
1- Forces and disturbances affecting space flight field, Solar wind, Aerodynamic forces, Grav				ht; Magnetic vity force.		6		4	2			
2- Space vehicle attitude sensing and measurement- Development of satellite attitude dynamic model.						9		6	3			

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4- Measurement and magnetometers and m magnetic torque.	actuation using magnet agnetic torque rods. Laws	6		4	2					
5-Sensors measuring velo devices.	3		2	1						
6- Spacecraft Actuation an magnetorquers and thr Reaction wheels	nd Control Devices, Reaction usters. , Selection and Sizin	n wheels, g of	9		6	3				
7- Other sensors, pressure	3		2	1						
Total Hours			45		30	15				
	Lectures	es (24) Pra Lat		ctical Training/ poratory (-)	Seminar/ Workshop (-)					
4. Teaching and Learnin	Class Ac	tivity (-)	Cas	e Study (6)	Projects (9)					
	E-learnir	earning (-)		ignments mework (6)	Other:					
5. Student Assessment Methods										
Assessment Sche	We	Week								
-Assessment 1: Class test	6 th	6 th week								
- Assessment 2: Class assi	Eve	Every other week (6 assignments)								
-Assessment 3; Project As	4 th	4 th week								
-Assessment 4; Presentation	N/A	N/A								
-Assessment 5; Midterm I	8 th	8 th week								
-Assessment 6; Final Example	End	End of semester								
Weighting of Assessments										
-Mid-Term Examination	159	15%								
-Final-term Examination	609	60%								
-Class assignments (Home	159	15%								
-Class Test (s)	109	10%								
-Presentation	N/A	N/A								
-Total	100	100%								
6. List of References										
Wertz, Spacecraft attitude determination and control, Kluwer Academic Publishers										
7. Facilities Required for Teaching and Learning										
Projector										
Course Coordinator: Prof. Mohamed Bahey Argoun										
Head of Department:	partment: Prof. Ayman Hamdy Kassem									